

**Korea Chapter Meeting @ SIGGRAPH2011**

# Supporting Mixed Reality Visualization in X3D

August 11, 2011

**Gun Lee**

gun.lee@hitlabnz.org

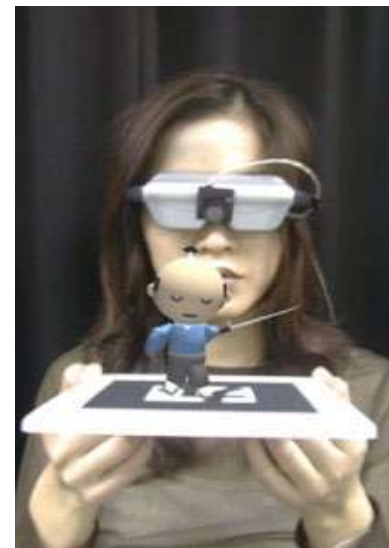


# Augmented Reality

- What is AR (Augmented Reality) ?
  - “Augmented Reality (AR) is a field of computer research which deals with the combination of real-world and computer-generated data.” – wikipedia.org
- Key Features of AR [R. Azuma 97]
  - Combines real and virtual images
  - Interactive in Real-Time
  - Registered in 3D Real World



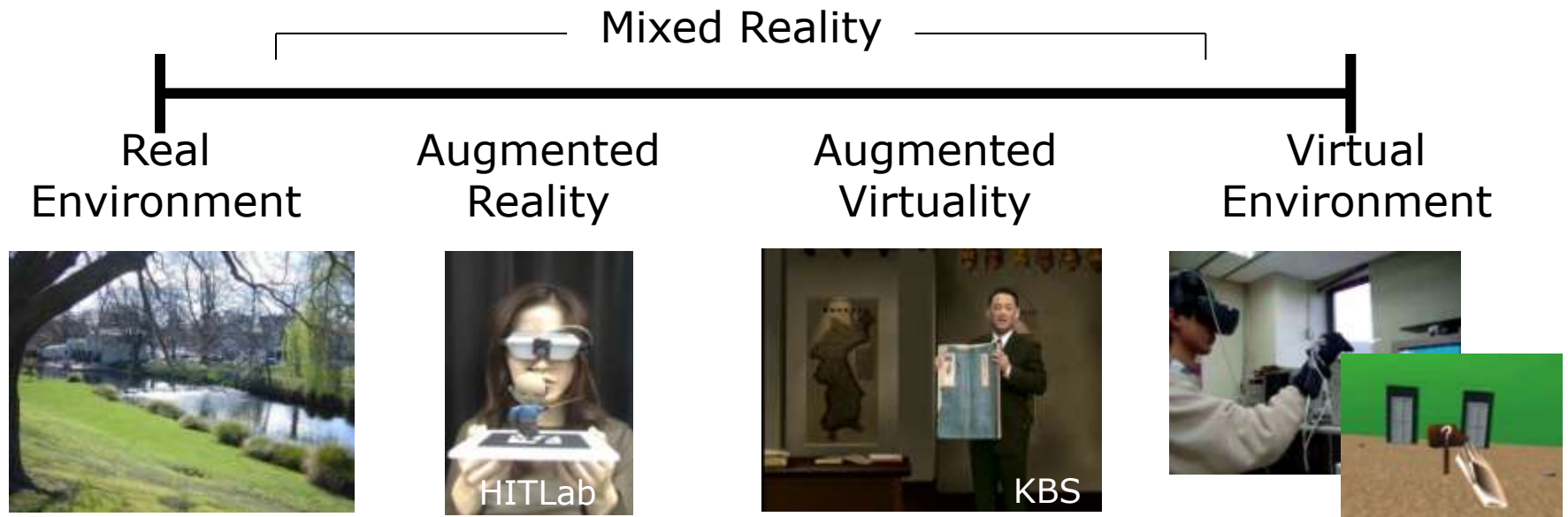
STAR System  
[HRL Laboratories, 1998]



ARToolkit  
[HITLab, Univ. of Washington, 1999]

# Mixed Reality

- What is MR (Mixed Reality) ?



[Paul Milgram's Reality-Virtuality Continuum (1994)]

# AR/MR Applications on the Web



AR Encyclopedia  
[metaio.com] 



Volvo Ocean Race  
Promotion, 2008




Smart Grid Promotion  
GE, 2009 




BMW Z4 Testrive Promotion,  
2009 



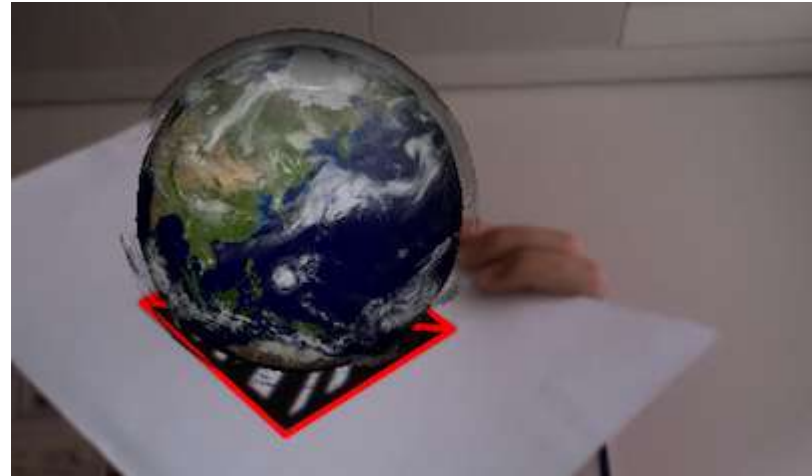
3D Experience Cerial Box,  
2009 [Dassault Systemes] 



Ray-Ban virtual mirror promotion,  
2009 [FittingBox] 

# AR Application with X3DOM

- X3DOM
  - HTML5 – WebGL
  - J. Behr, Fraunhofer IGD
- FLARToolkit
  - Requires Flash Plug-in
  - Flash version of AR Toolkit
- Layers X3D scene on top of Flash viewport
- A good platform for experimenting and implementing AR/MR functions as standards
  - Users might benefit more if those functions provided by FLARToolkit becomes a standard in X3D, so that they would not need to handle repetitive wiring between flash and X3D.



# Requirements of X3D to be AR/MR capable

- Adding real world view
  - Live video (esp. camera on the user's computer)
  - Merging real and virtual image correctly
    - Camera calibration
    - Occlusion
    - Shadow
    - Reflection & Refraction
  - Live movie texture
- Registration
  - Static - Relationship between real and virtual spaces
  - Dynamic - Tracking user's viewpoint
- Real-time Interactivity
  - Tracking (users & other real world objects)

# Live Video Support

- Fraunhofer + Korean Chapter

- CameraSensor:X3DDirectSensorNode {  
    SFImage       [out]       value  
    SFBool       [out]       on        FALSE  
    SFMatrix4f   [out]       projmat  "1 0 0 0 ... "  
    SFBool       [out]       tracking   FALSE  
    SFVec3f      [out]       position  
    SFRotation   [out]       orientation  
}

# Video on the Background

- Current Background Nodes
  - Describes 3D background that changes according to the viewpoint navigation
  - For AR applications, we need to make video on the background independent from the viewpoint navigation
- ImageBackground Node

```
...  
<CameraSensor DEF='cam'/>  
<ImageBackground DEF='bg' image=''/>  
  <ROUTE fromNode='cam' fromField='image'  
    toNode='bg' toField='image'/>  
...
```



# MovieTexture / MovieBackground

## - An Alternative way to CameraSensor

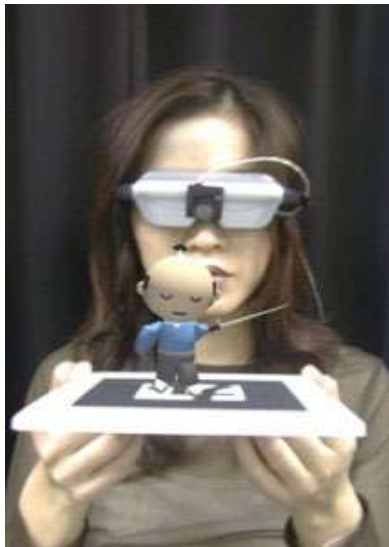
- Making MovieTexture user reconfigurable
- No big change to current X3D spec, no routing
- Add a standard behavior of MovieTexture to
  - Ask user to choose the video source (file or camera) if url field is empty (or specific token is used)

```
...  
<Appearance>  
  <MovieTexture loop='true' url='USER_RECONFIG'/>  
</Appearance>  
...
```

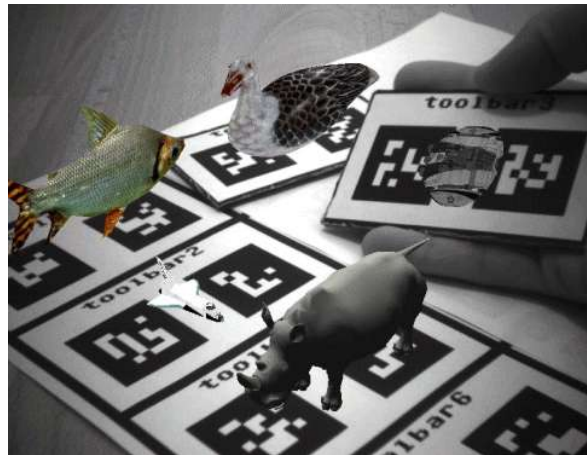
```
...  
<MovieBackground url="" />  
...
```

# Tracking

- Sensor based Tracking
  - Ultrasonic, Electromagnetic, Mechanical, Optical motion capture
- Computer Vision based Tracking
  - ARToolkit (HITLab), ARTag (Canadian NRC), BazAR (EPFL)



[ARToolkit, HITLab]



[ARTag, CNRC]

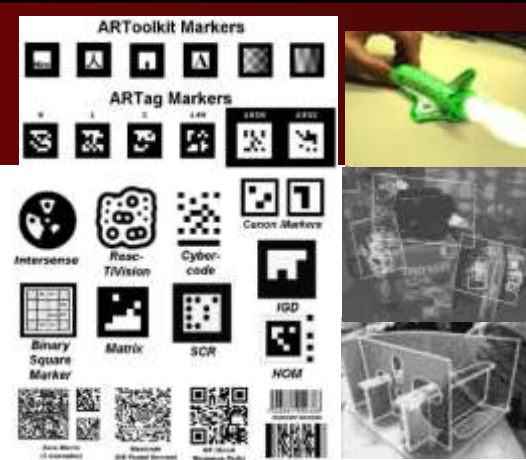


[BazAR, EPFL]

# Tracking (cont'd)

- Tracking methods

- Too many/various to be standardized...
- Leave to browser implementation, X3D only provides interfaces to the tracking results
  - Browser decides (or provides an interface to choose) which tracking methods/devices to use/support
  - Tracking technology in use is hidden to X3D scene, and only the tracking results are provided into X3D scene
  - X3D authors do not have to worry about the hardware system setup in run-time



```
TrackingSensor:X3DDirectSensorNode {  
    SFVec3f      [out]    position  
    SFRotation  [out]    orientation  
}
```

# Camera Calibration

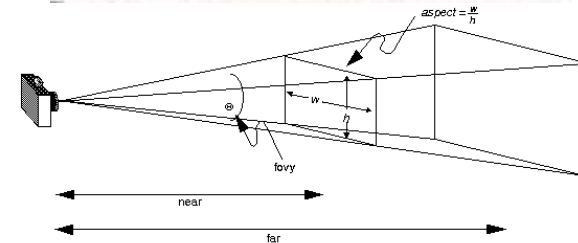
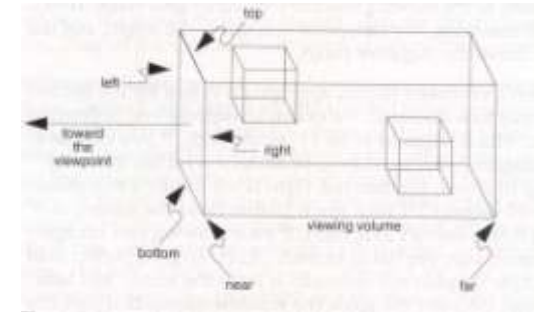
- Standard Viewpoint Nodes

- OrthoViewpoint

- Orthographic projection
- fieldOfView in min-max box

- Viewpoint

- Perspective projection
- fieldOfView in radian



- Viewpoint node for MR visualization needs ...

- Directly assigning projection matrices

- Assigning values from LiveCamera

- Easily support tracking information

- Position, orientation field

- Defined in X3DViewpointNode abstract type

# Camera Calibration

## ■ MatrixViewpoint

```
MatrixViewpoint : X3DViewpointNode{  
  SFMatrix4f      [in]      projmat  
  SFVec3f         [in,out]   position  
  SFRotation      [in,out]   orientation  
  SFNode          [in,out]   cameraSensor  
}
```

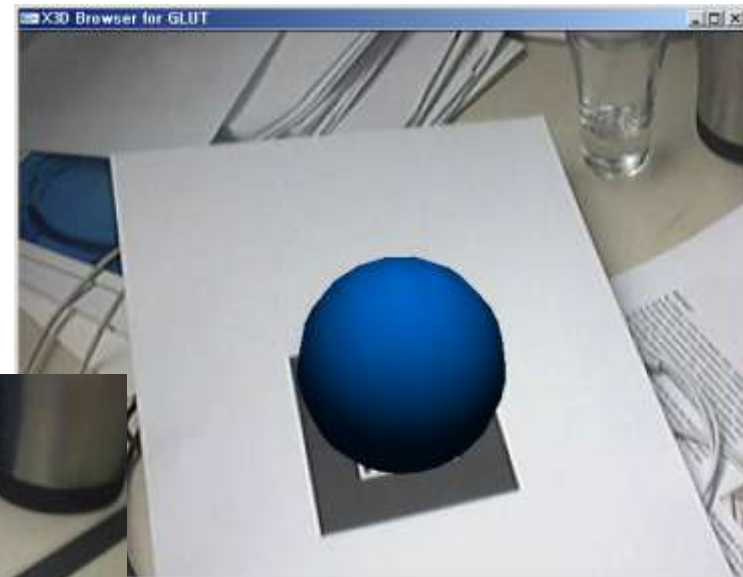
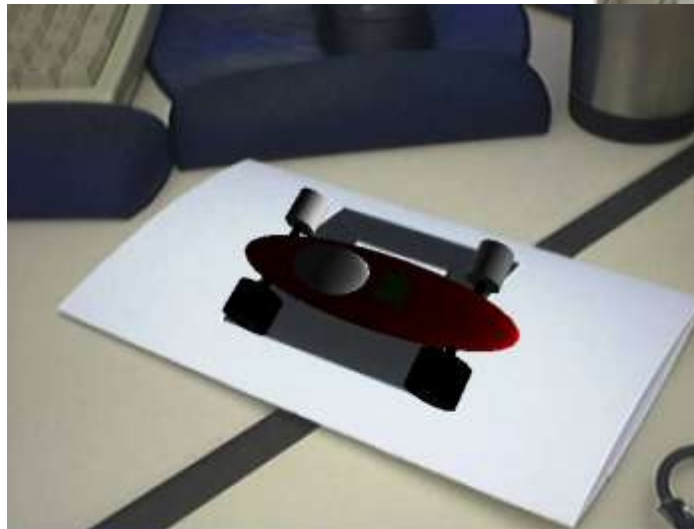
```
<Scene>  
  <CameraSensor DEF='USBCam1'/>  
  <MatrixViewpoint liveCamera='USBCam1'/>  
  <Shape> ... </Shape>  
</Scene>
```

Or, using routes...

```
<Scene>  
  <CameraSensor DEF='USBCam1'/>  
  <MatrixViewpoint DEF='MRView'/>  
  <Shape> ... </Shape>  
  <ROUTE fromNode='USBCam1' fromField='projmat'  
        toNode='MRView' toField='projmat'/>  
  <ROUTE fromNode='Tracker' fromField='position'  
        toNode='MRView' toField='projmat'/>  
  <ROUTE fromNode='Tracker' fromField='orientation'  
        toNode='MRView' toField='projmat'/>  
</Scene>
```

# All together – X3D might look like ...

```
...  
<Scene>  
  <CameraSensor DEF='cam' />  
  
  <Background DEF='bg' />  
  <ROUTE fromNode='cam' fromField='image' toNode='bg' toField='image' />  
  
  <MatrixViewpoint cameraSensor='cam' />  
  
  <Transform translation="0 0 40">  
    <Shape>  
      <Appearance>  
        <Material diffuseColor='0 0.5 1' />  
      </Appearance>  
      <Sphere radius="40" />  
    </Shape>  
  </Transform>  
</Scene>  
...
```

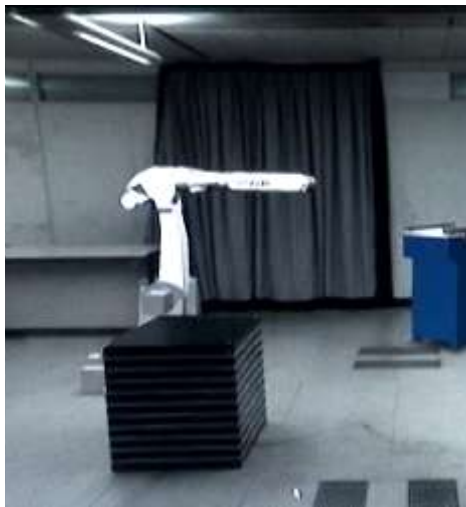


# Looking forward to...

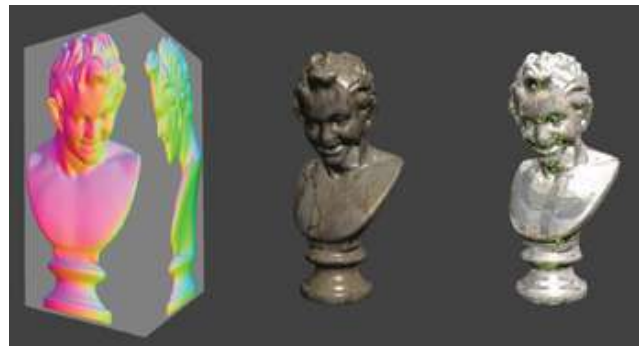
- Correct occlusions and Augmented Virtuality
  - Masking - Ghost object rendering
  - Depth image (e.g. stereo image matching, depth camera)
    - Pixel = rgb**d**
    - Got popular with MS Kinect
    - Support Depth image in X3D nodes (SFImage, MovieBackground, MovieTexture)
  - Heuristics (chroma keying with skin color)
    - Add KeyColor field to MovieTexture



Depth Image  
[Wikipedia]



Masking [ETRI]



Relief Texture  
[NVIDIA Cg Tutorial]



Chroma Keying / Augmented Virtuality  
[Kudlian Software]

# Looking forward to...

- OpenSceneGraph ([www.openscenegraph.org](http://www.openscenegraph.org))
  - C++ based scene graph library
  - Large user community
  - Open source, commercial friendly license
- osgART
  - AR plug-in to OSG
  - Different tracking technologies as plug-ins
- X3D support is missing !?





- Started up and running since June 2011
- Active Members:
  - Gun Lee (HIT Lab NZ)
  - Gerard J. Kim (Korea Univ.)
  - Yvonne Jung, Sabine Webel, Johannes Behr (Fraunhofer IGD)
  - Oliver Neubauer (Bitmanagement)
  
- Slow, but steady
- Looking forward to gain more speed with more participants
  
- Current tasks
  - Requirement and use cases
  - Comparing and merging proposals

# **Lots of things to do @ AR WG**

**Please join us!  
You are more than welcome!**

Thank you!

Gun Lee  
gun.lee@hitlabnz.org