

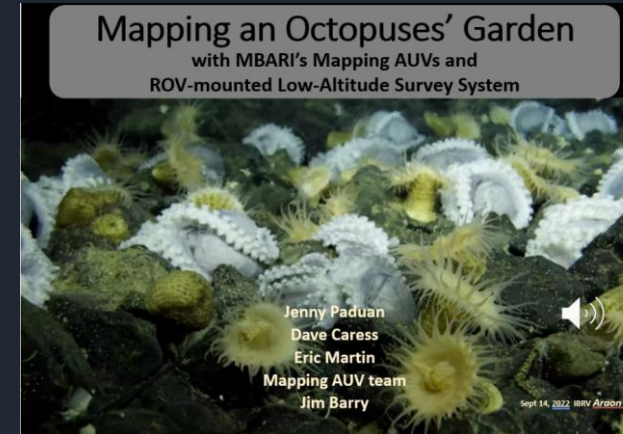
# X3D Use Cases

## Versar: Geospatial and Digital Solutions



Versar leverages X3D's geospatial capabilities to create interactive environmental analysis tools. Their applications help clients visualize environmental impact assessments, infrastructure planning, and resource management scenarios through intuitive 3D interfaces that integrate multiple data sources into cohesive geospatial visualizations.

## MBARI: Mapping of the Seafloor



The Monterey Bay Aquarium Research Institute uses X3D for visualizing complex underwater terrain and biological habitats. Their systems combine bathymetric data, underwater photography, and biological observations into interactive 3D environments that help scientists study marine ecosystems in unprecedented detail.

X3D provides the tools needed to create meaningful interactive visualizations that help stakeholders understand complex spatial relationships

# Web3D Consortium: Powering 3D on the Web

Founded in 1995, the Web3D Consortium has been at the forefront of developing open standards for real-time 3D communication on the web for **30 years**.

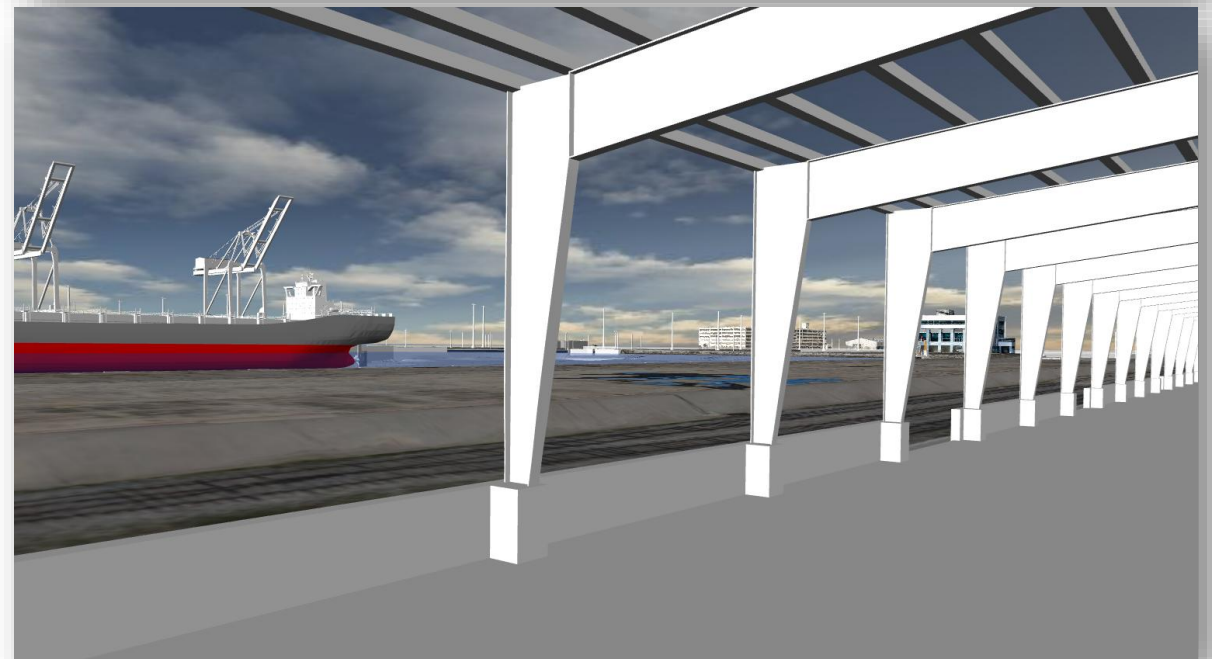
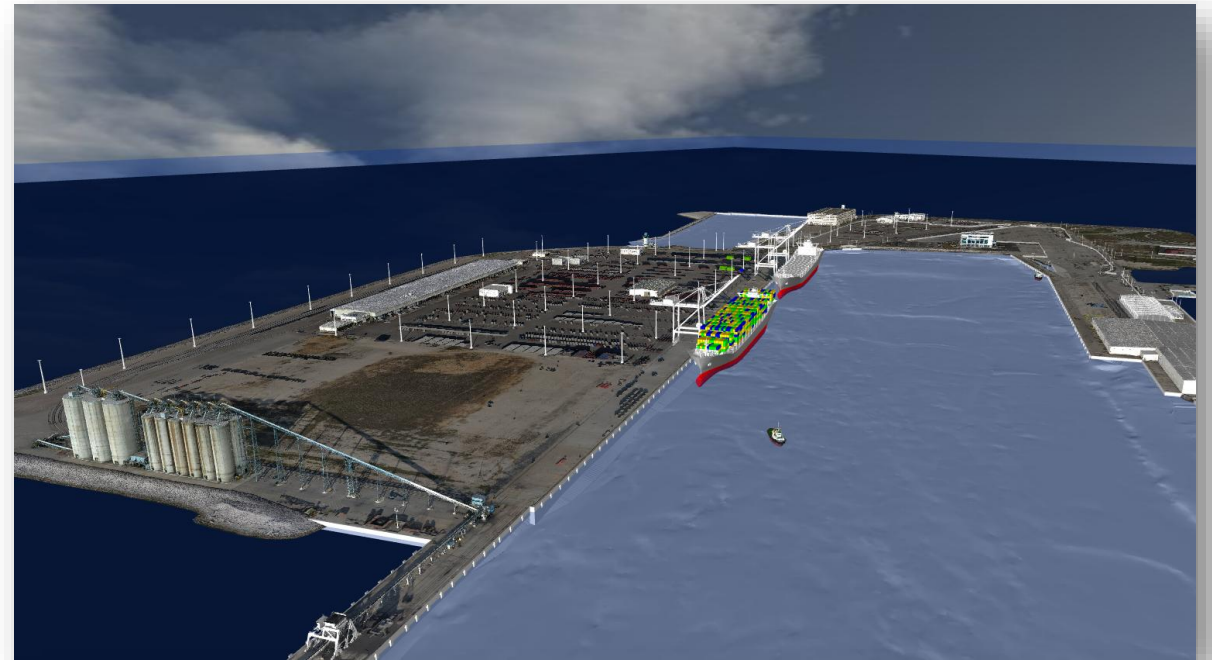
Our mission is to develop and promote **royalty-free** standards that enable the creation, delivery, and playback of interactive 3D content across various platforms and devices.

The consortium brings together experts from academia, government, and industry to ensure that 3D technologies remain accessible, interoperable, and future-proof.





- Program and Project Management Company
- Geospatial and Digital Solutions Group
- Partners with:
  - Web3D Consortium
  - Open Geospatial Consortium
  - Naval Post Graduate School
  - Virginia Tech
- Government and DOD Customers
  - Engineering
  - Geospatial
  - Planning
  - Management
  - Consultation
  - Training
  - Products and Services





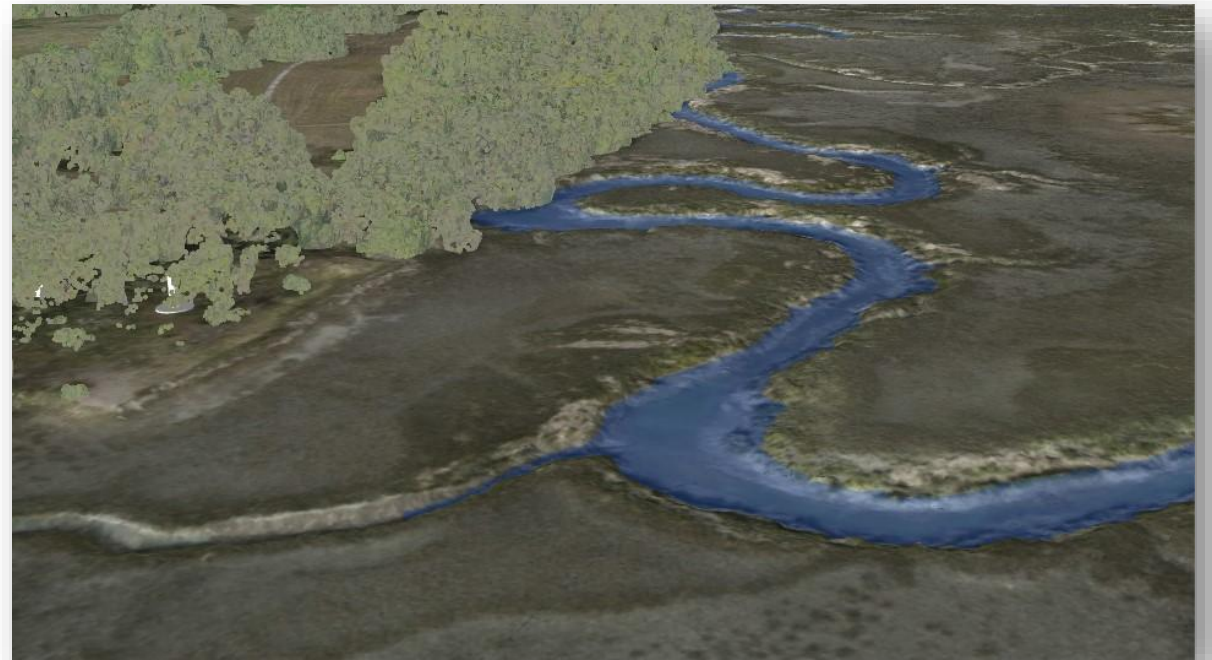


- Information and Connectivity
  - Build on and improve existing data methodologies and pipelines
  - Facilitate creation, interoperability, and access to data
- X3D Virtual Environments and the Internet
  - Non-proprietary solution
  - Implemented and authorized for use by the government
  - Minimal edge computing requirements
  - Access to data regardless of location and software
  - Findable, Accessible, Interoperable, Reusable
  - Efficiency and Standardization





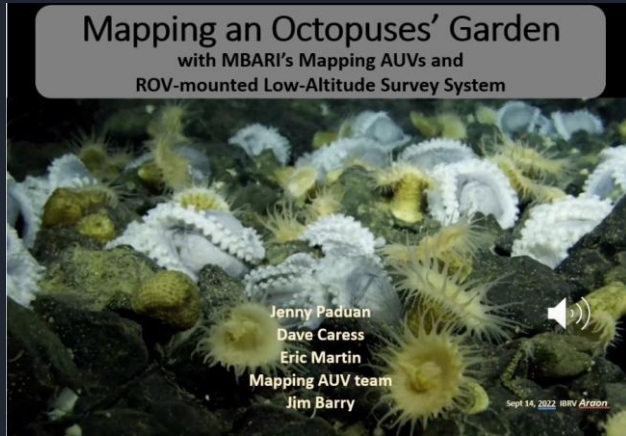
- X3D Capability and Observations
  - Terabytes of data collected or aggregated
  - Conversion and Transformation
  - Gigabytes or Megabytes Rendered and Shared
  - Maintain quality and fidelity of data
  - Data interaction and investigation
- Value to Our Customers
  - Currently being implemented
  - Allows for critical collaboration and decision making
  - Precision
  - Customizable
  - Integrable and relatable
  - Performant
  - Accessible





# X3D Geospatial Use Cases

## 01 MBARI: Mapping an Octopuses' Garden



The Monterey Bay Aquarium Research Institute uses X3D for visualizing complex underwater terrain and biological habitats. Their systems combine bathymetric data, underwater photography, and biological observations into interactive 3D environments that help scientists study marine ecosystems in unprecedented detail.

# Mapping an Octopuses' Garden

with MBARI's Mapping AUVs and  
ROV-mounted Low-Altitude Survey System



Jenny Paduan  
Dave Caress  
Eric Martin  
Mapping AUV team  
Jim Barry



Sept 14, 2022 IBRV *Araon*

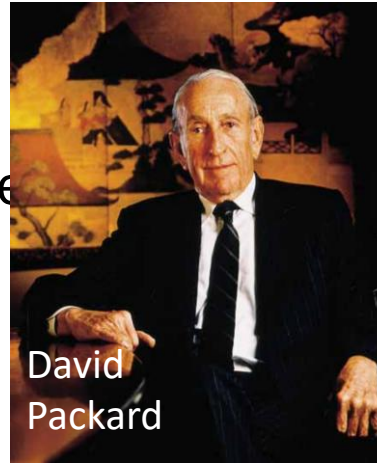




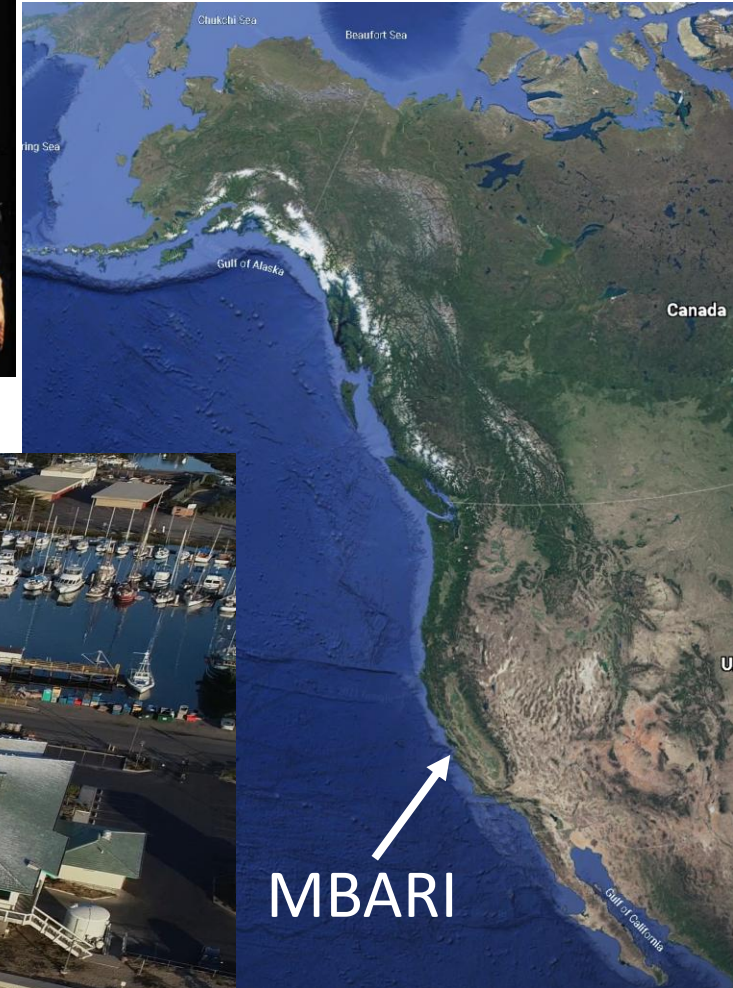
## Monterey Bay Aquarium Research Institute

Founded in 1987

Funding from the David and Lucile  
Packard Foundation



David  
Packard



MBARI



Moss Landing, CA







# MBARI operates three ships and an array of seagoing robots to study the oceans

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R/V Rachel Carson



R/V Paragon



Seafloor rover



R/V Western Flyer



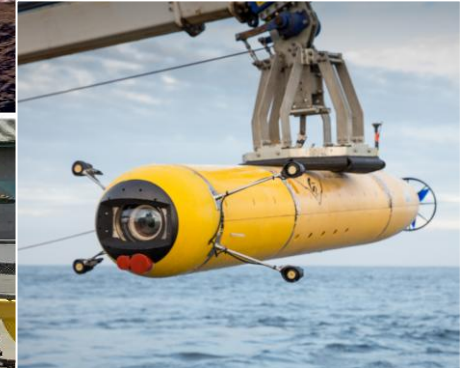
Gulper AUV



ROV Ventana



Long-range AUVs





## AUV

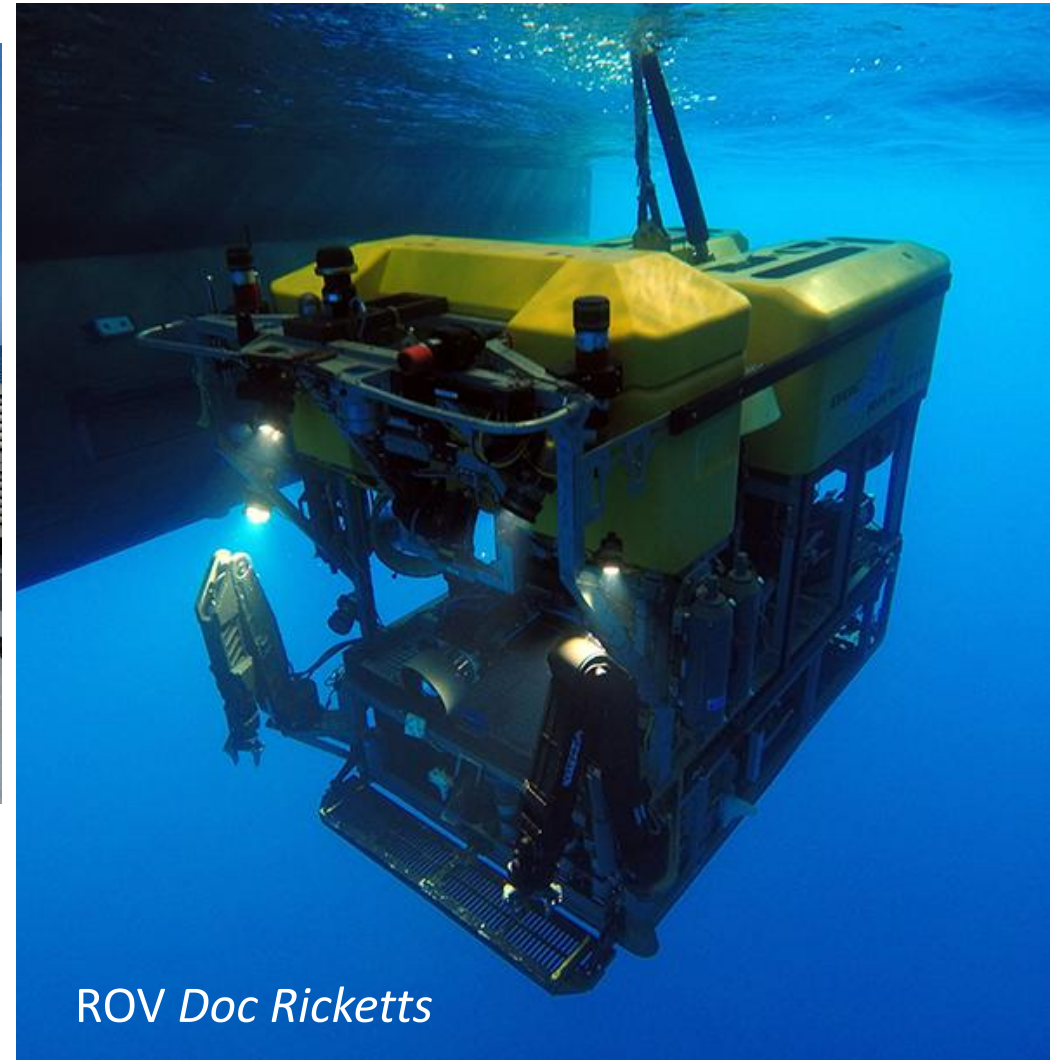
Autonomous Underwater Vehicle

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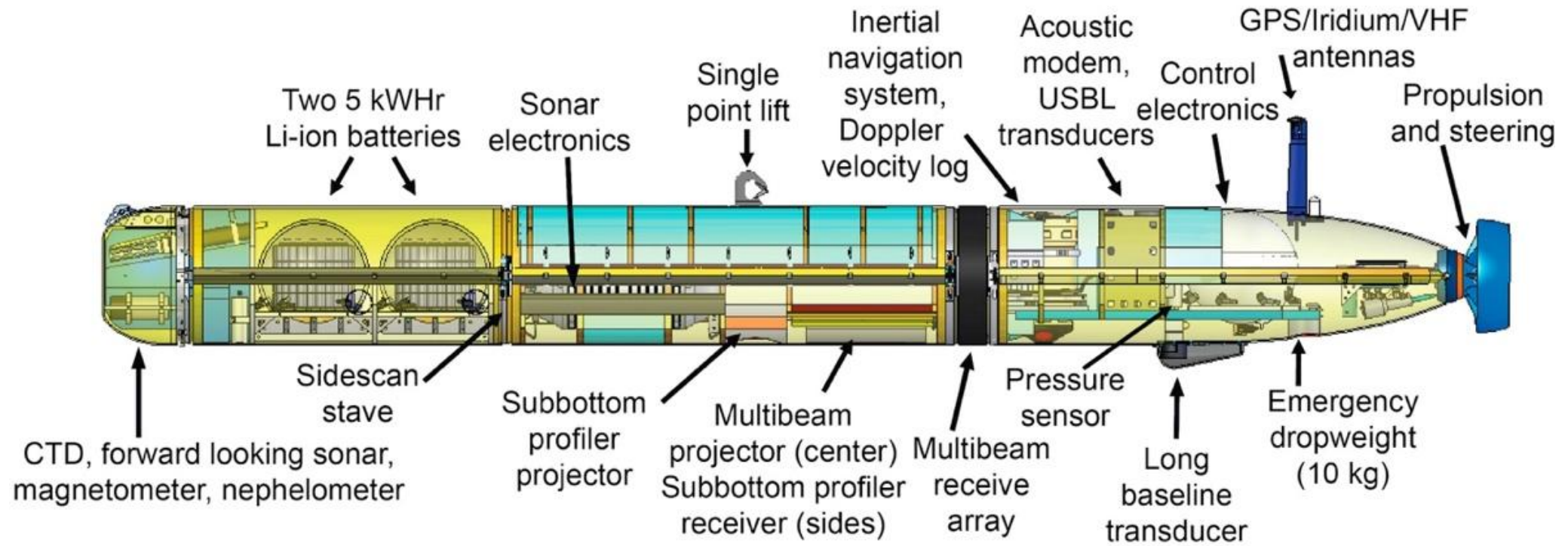


## ROV

Remotely-operated vehicle



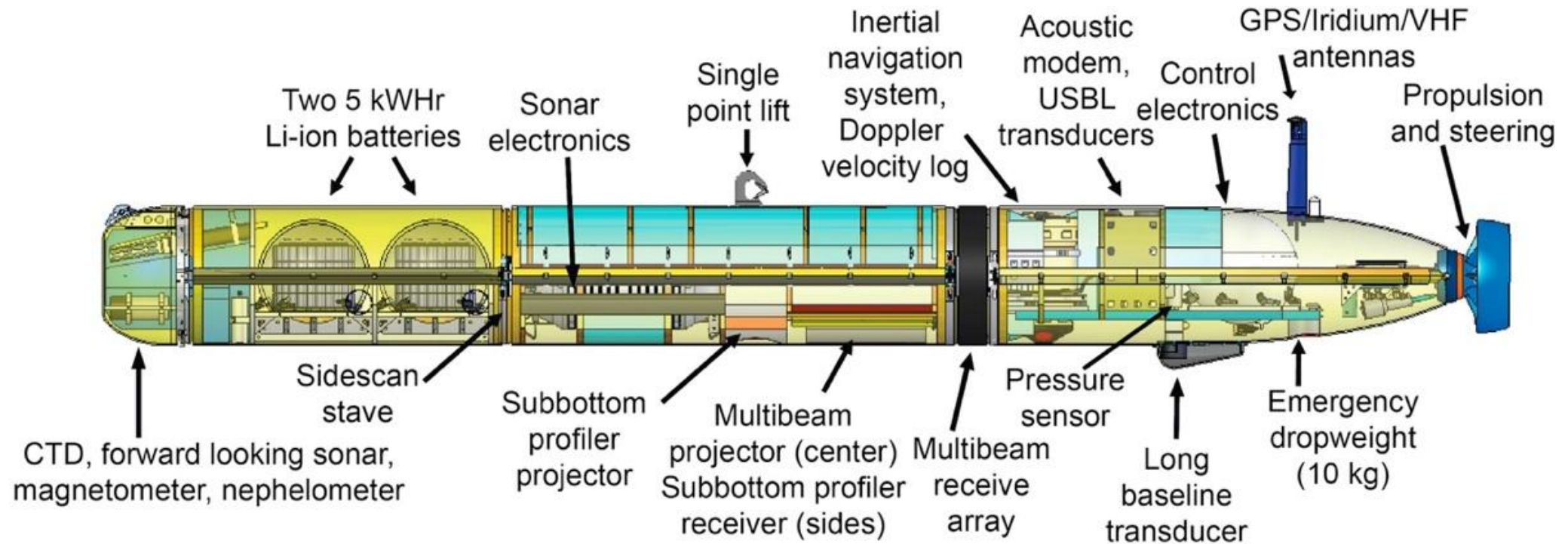
# Mapping AUV - schematic





# Mapping AUV - schematic

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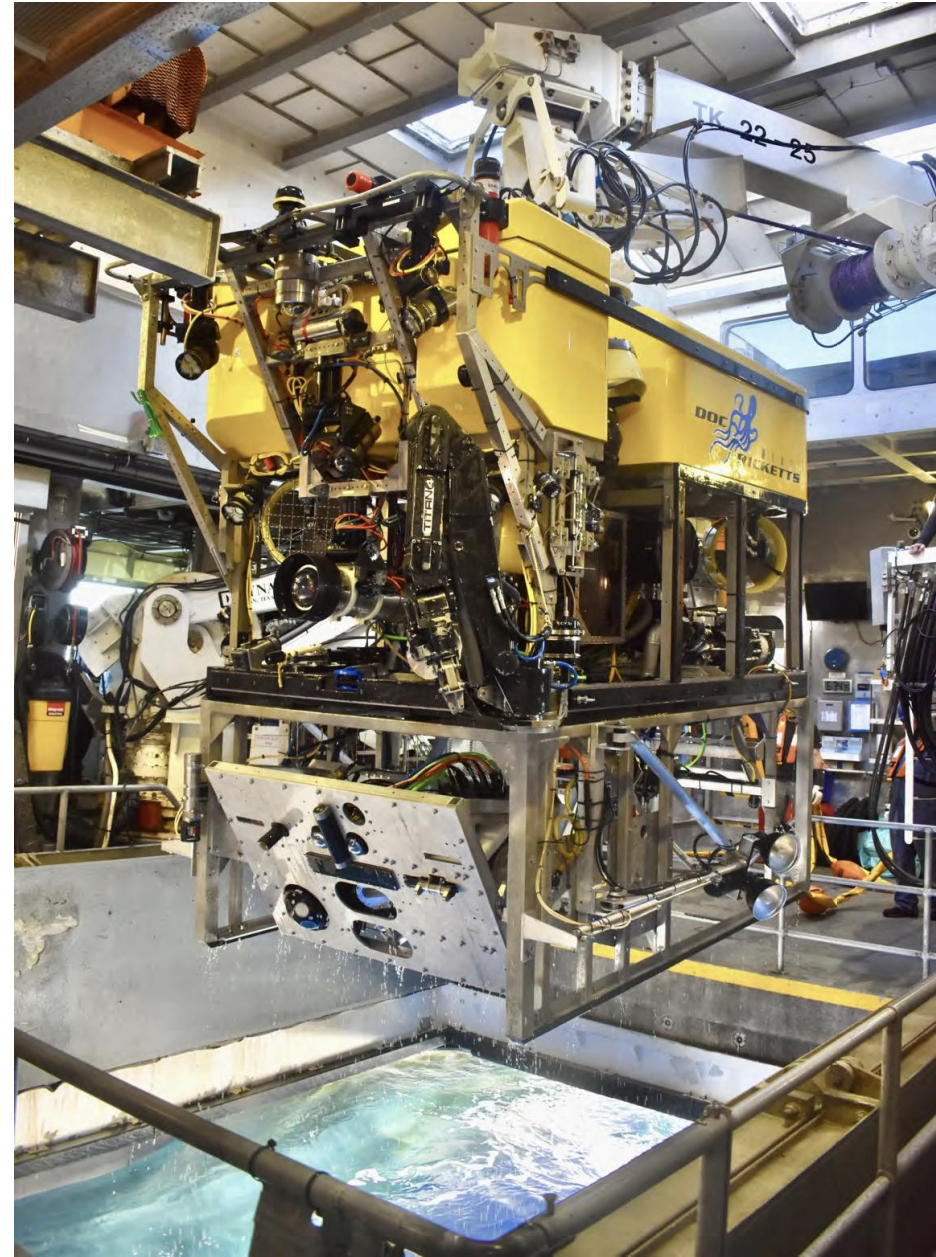


Fly 50 m above the seafloor for 1-m resolution data

# Low-altitude survey system (LASS)

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ROV *Doc Ricketts*





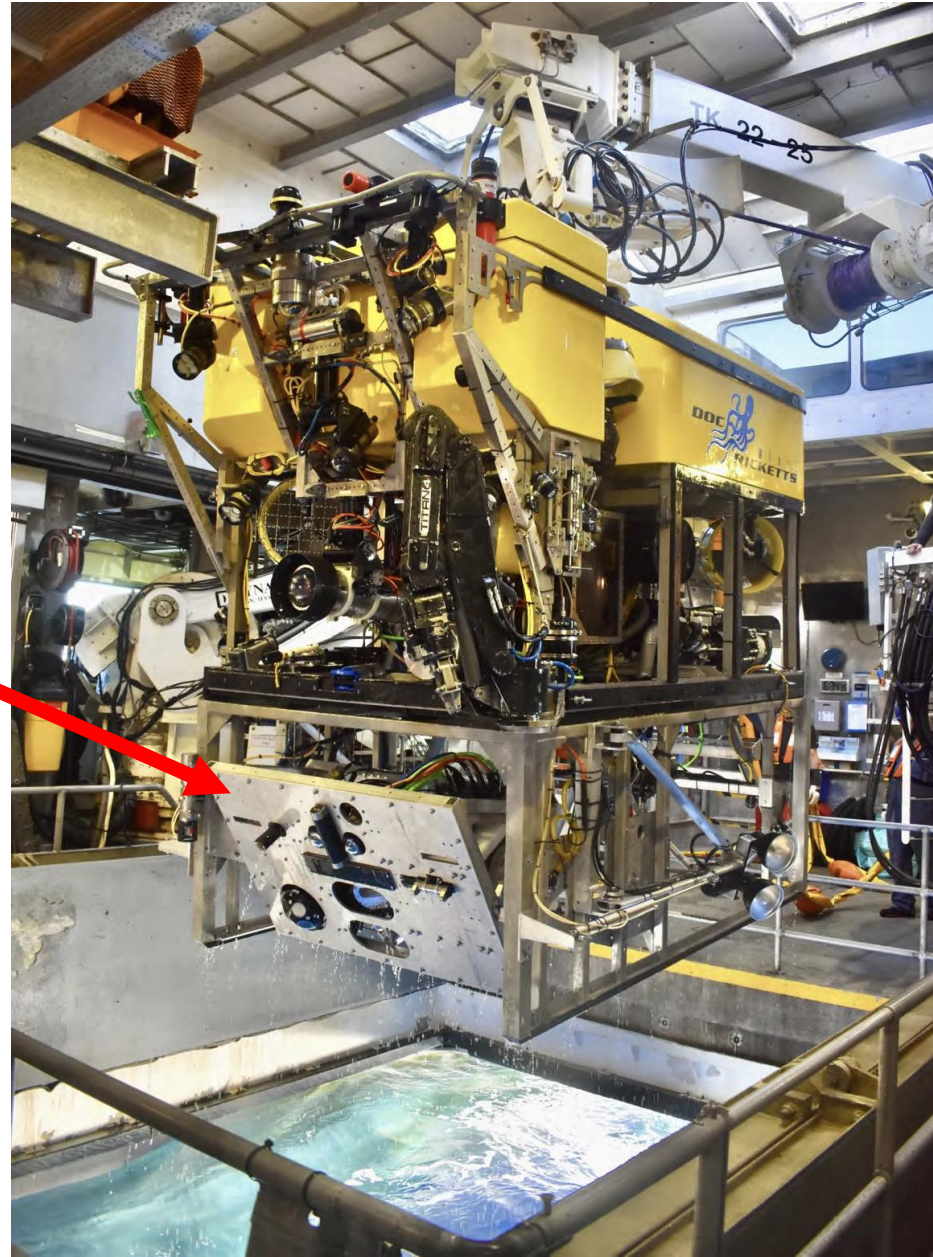
# Low-altitude survey system (LASS)

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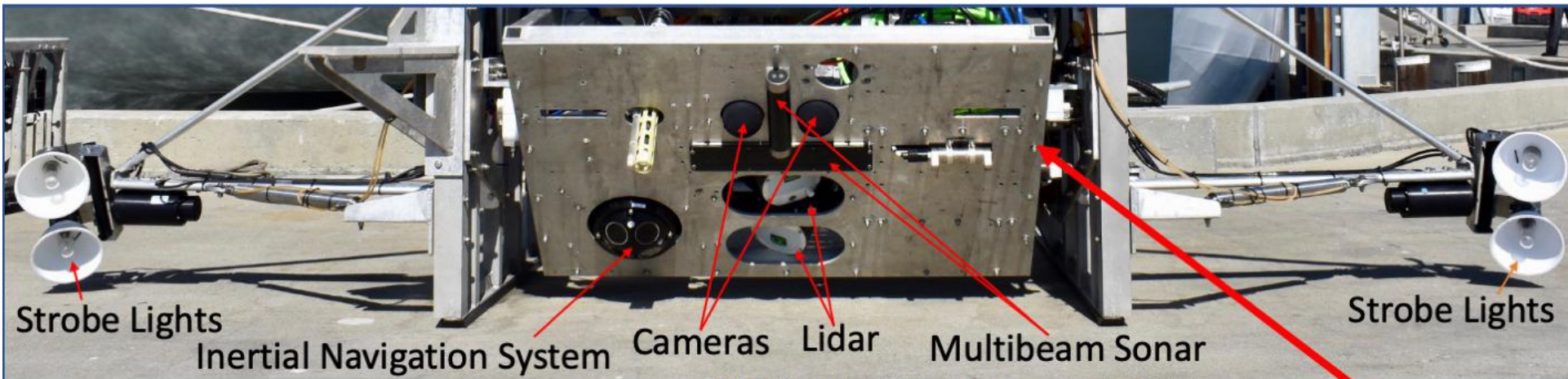
ROV *Doc Ricketts*

LASS toolsled

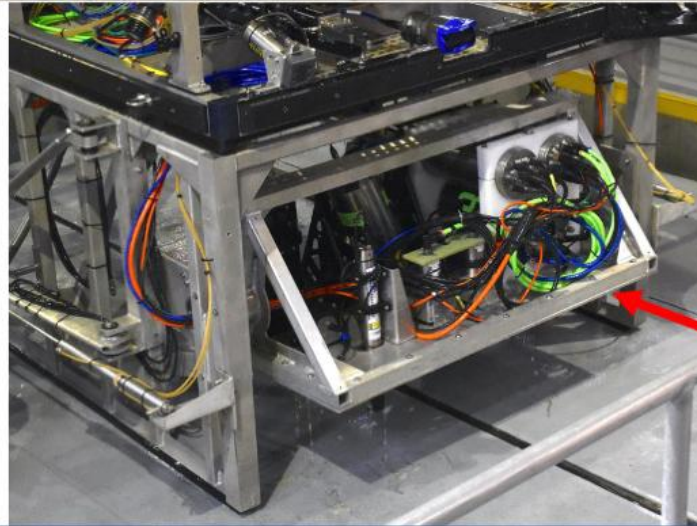
- Flown autonomously
- 3 m above seafloor
- 3 m wide line spacing



## Low-altitude survey system: sensors



- Wide Swath Lidar (WiSSL)
- Multibeam sonar
- Stereo color cameras + strobes
- Inertial Navigation System
- Sensor frame and strobes rotate to point at the seafloor regardless of slope



Sensor frame pointing 45° forward

Sensor frame pointing straight down



## Low-altitude survey system: articulating frame

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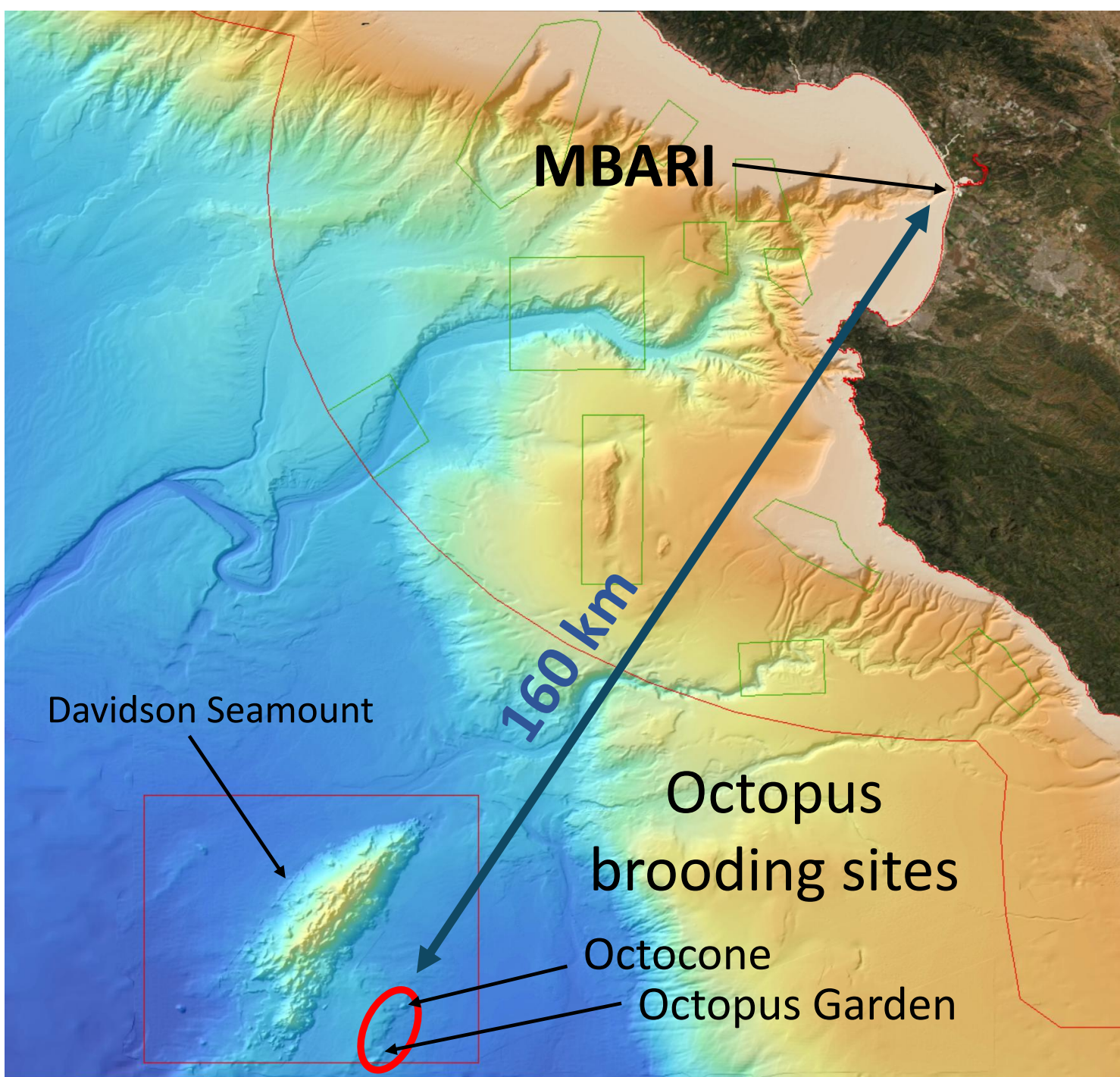
*Muusoctopus robustus* (a deepwater octopus)

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Feeding on a whale-fall







# *Muusoctopus* reproductive biology

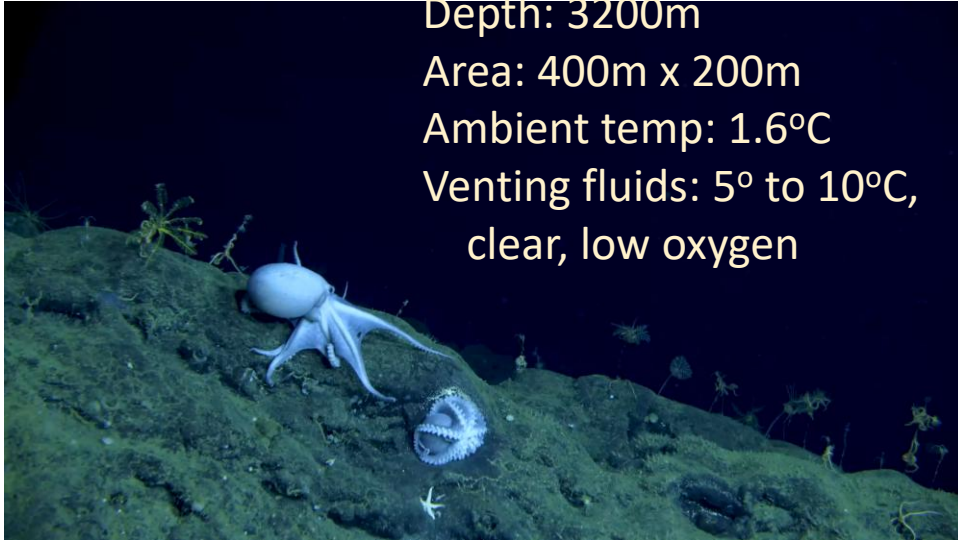
## Octopus Garden:

Depth: 3200m

Area: 400m x 200m

Ambient temp: 1.6°C

Venting fluids: 5° to 10°C,  
clear, low oxygen



Receptive female?



Mating



Incubation



Hatching



Death



# Mapping an Octopuses' Garden

with MBARI's Mapping AUVs and  
RCV mounted Low-Altitude Survey System



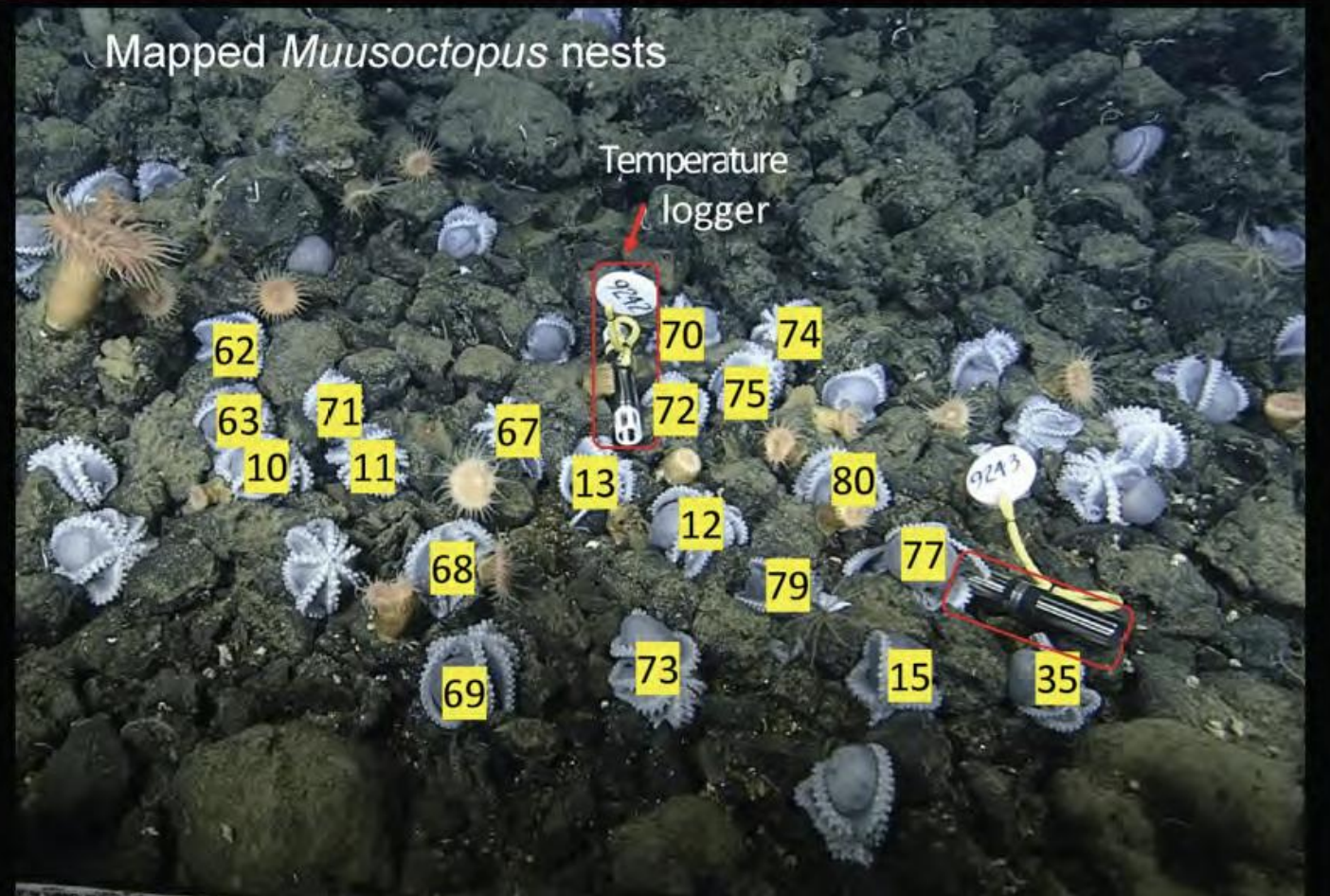


# *Muusoctopus* reproductive biology

## Field program

Revisit marked nests

- Temperature
- Oxygen
- Embryo condition
- Female identity





Questions that can be addressed by our combination of acoustic and optical mapping:

- How many octopuses are there?
- How many are brooding, wandering, or dead?
- How is their distribution related to the shape and character of the seafloor habitat?
- What other animals are there?



## Mapping Octopus Garden with the AUVs

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From the R/V *Rachel Carson*  
February, 2022



## Mapping Octopus Garden with the AUVs

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From the R/V *Rachel Carson*  
February, 2022



## Mapping Octopus Garden with the AUVs

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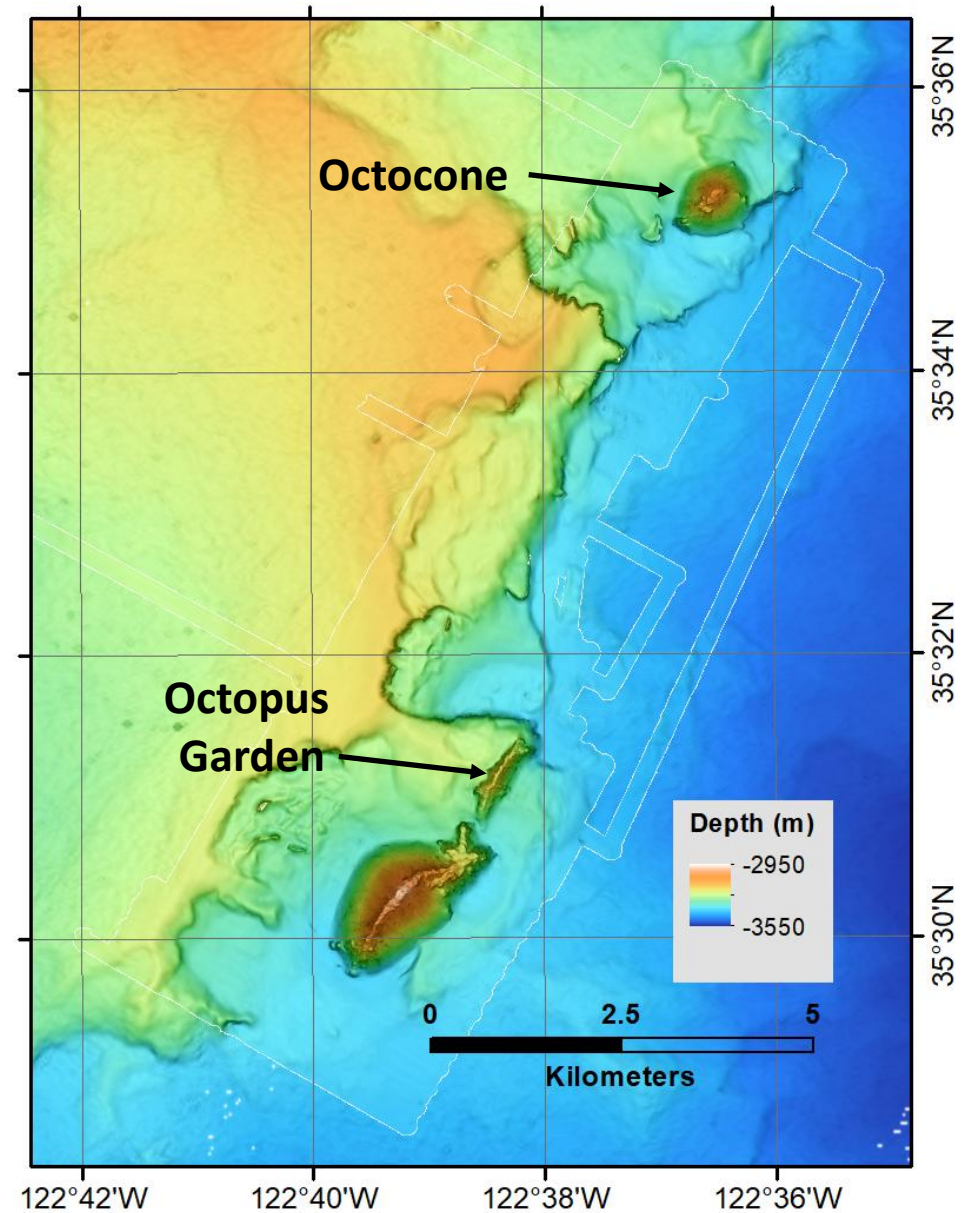
From the R/V *Rachel Carson*  
February, 2022



# Mapping Octopus Garden with the AUVs

February, 2022

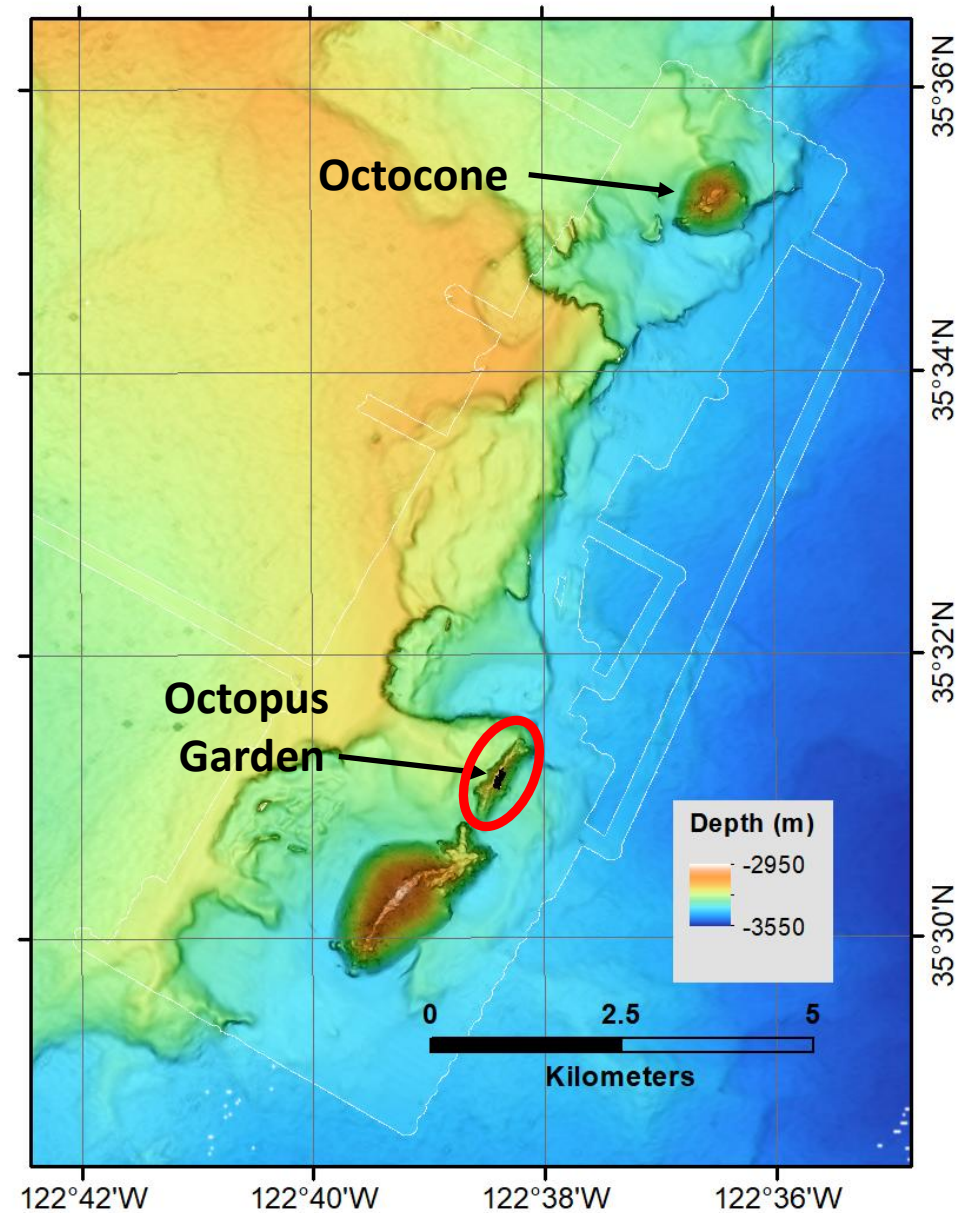
- AUV missions: 6
- Area: 54 km<sup>2</sup>
- Both brooding sites covered



# Mapping Octopus Garden with the Low-Altitude Survey System

April, 2021

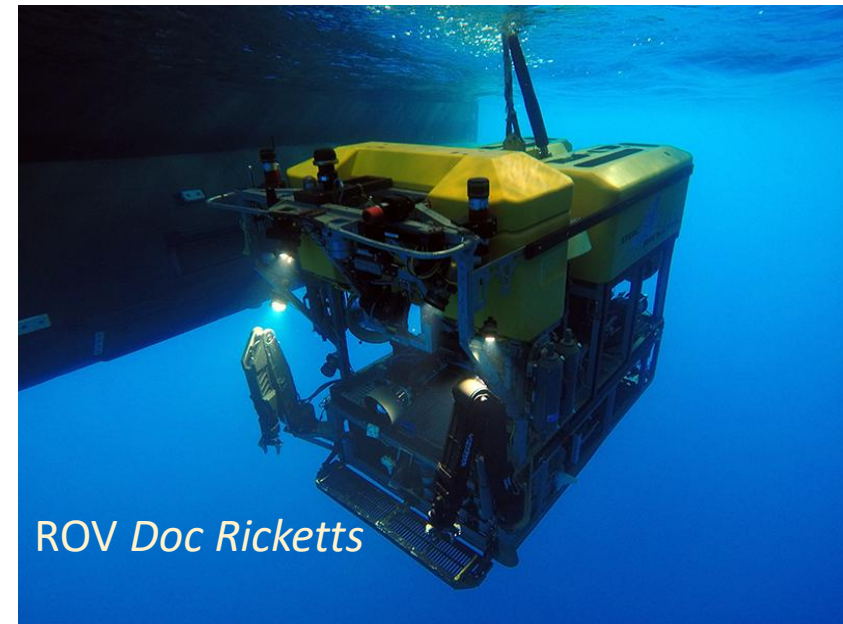
- LASS missions: 2
- Area: 245 m by ~95 m
- Part of Octopus Garden





# Mapping Octopus Garden with the Low-Altitude Survey System

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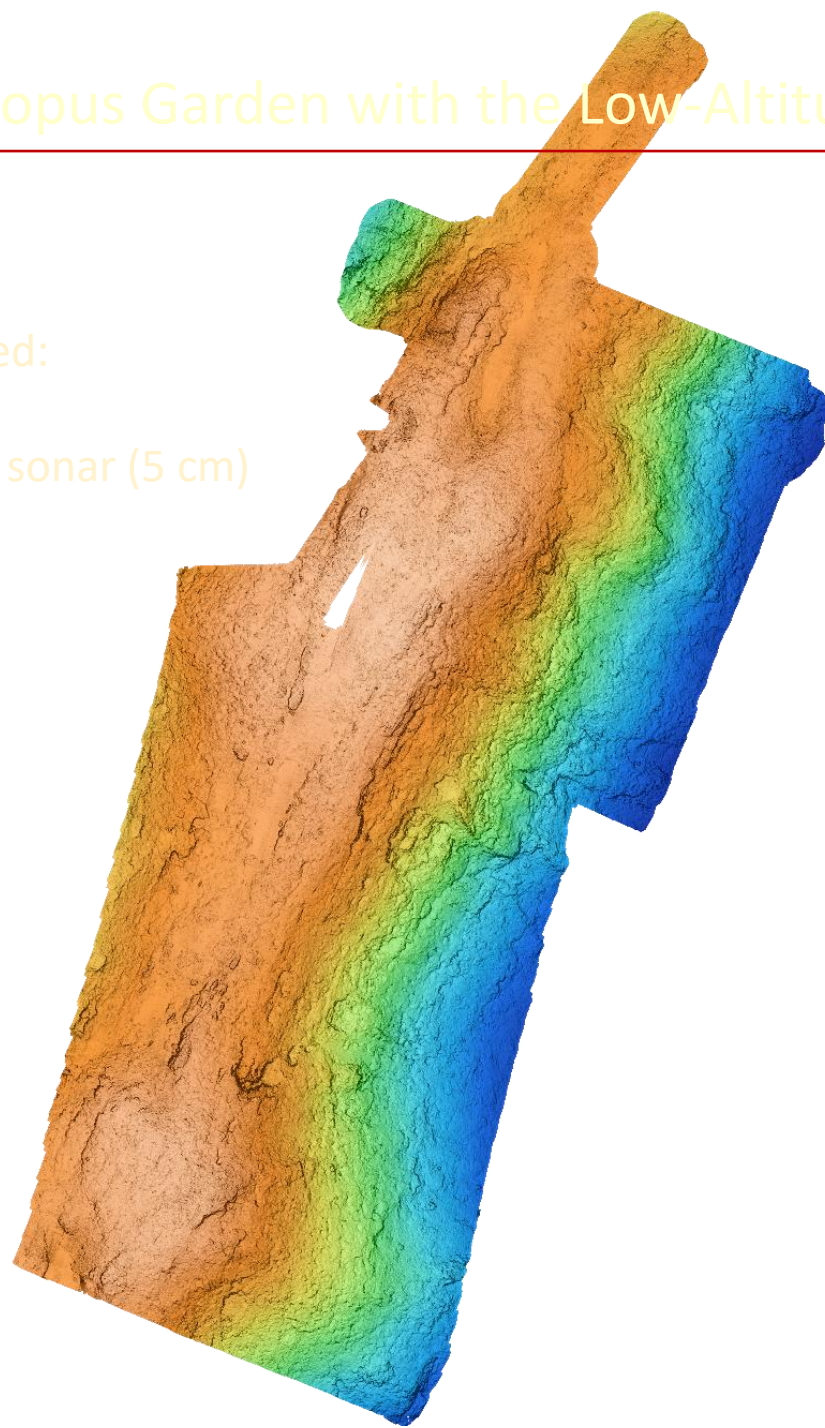




# Mapping Octopus Garden with the Low-Altitude Survey System

Co-navigated:

Multibeam sonar (5 cm)



0 meters

Stereo still  
cameras  
(2 mm)

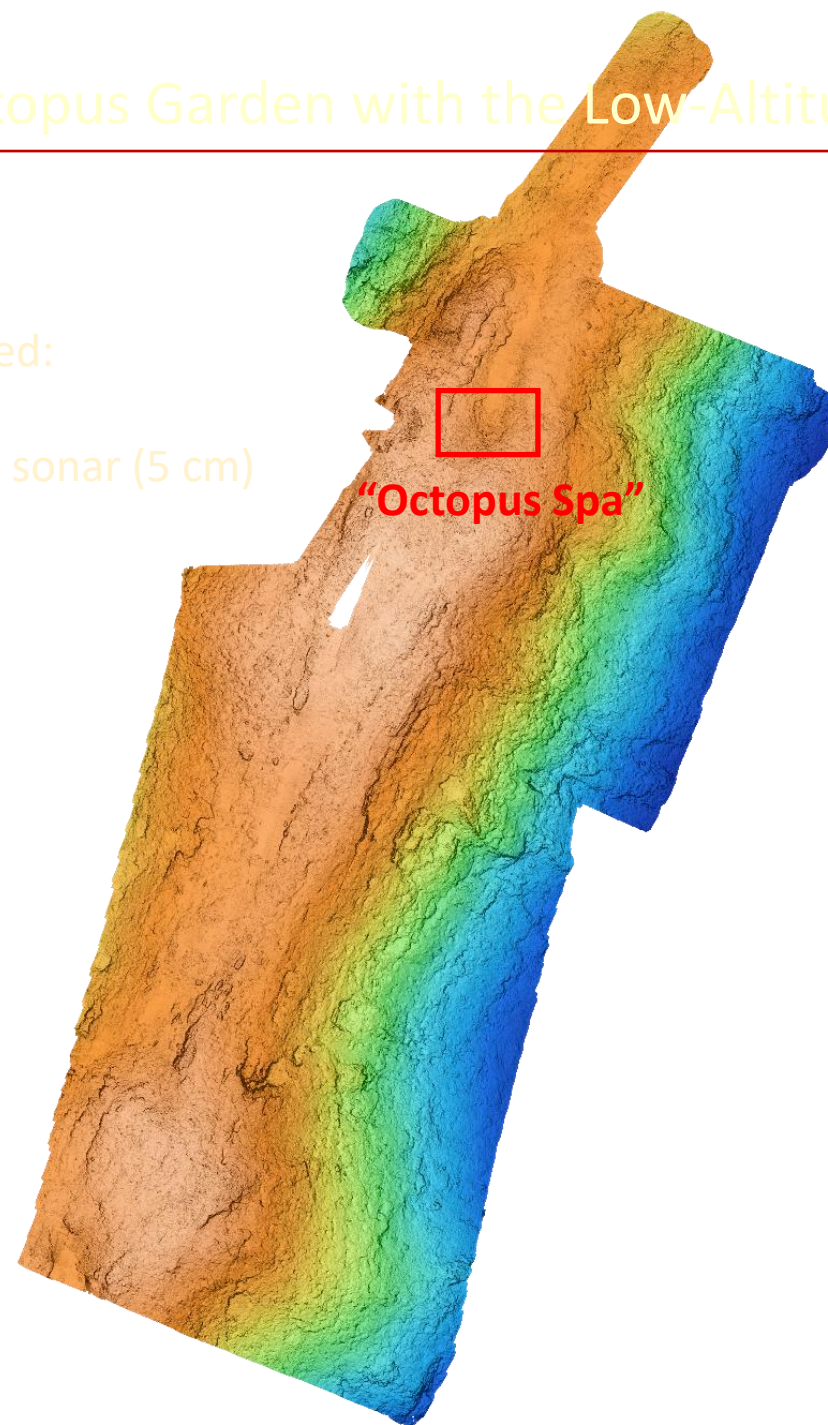




# Mapping Octopus Garden with the Low-Altitude Survey System

Co-navigated:

Multibeam sonar (5 cm)

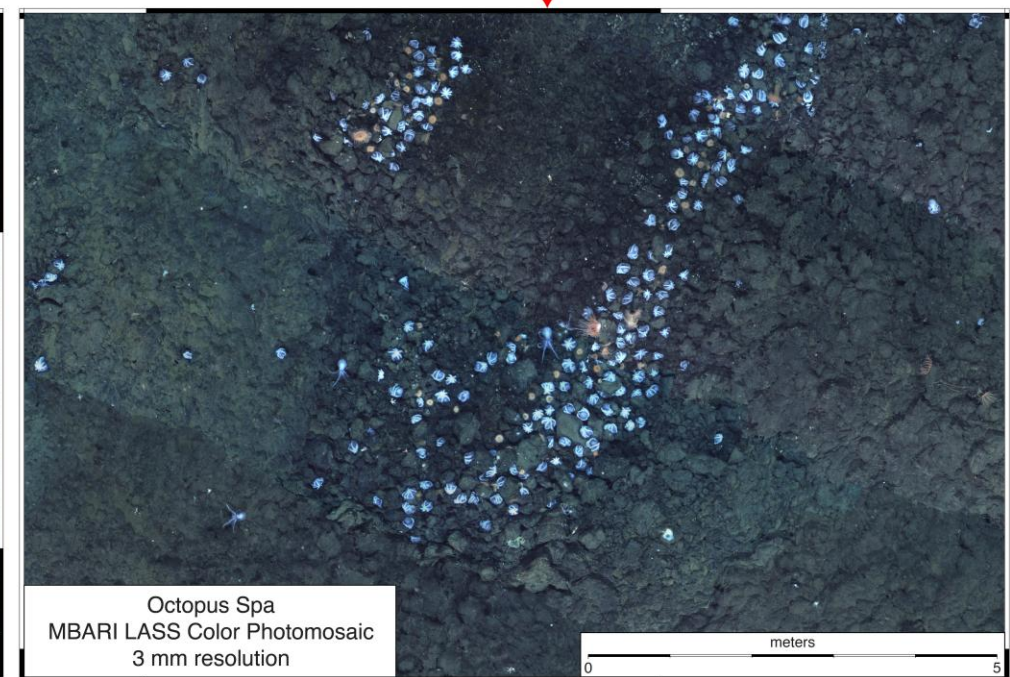
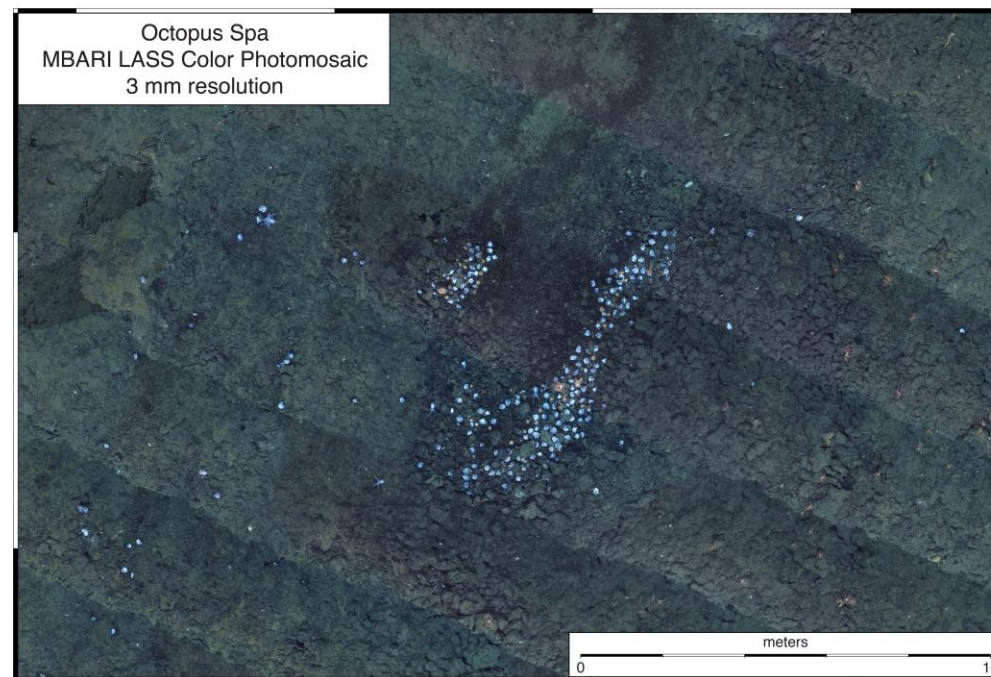
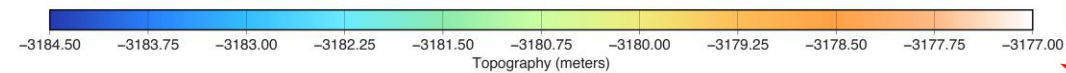
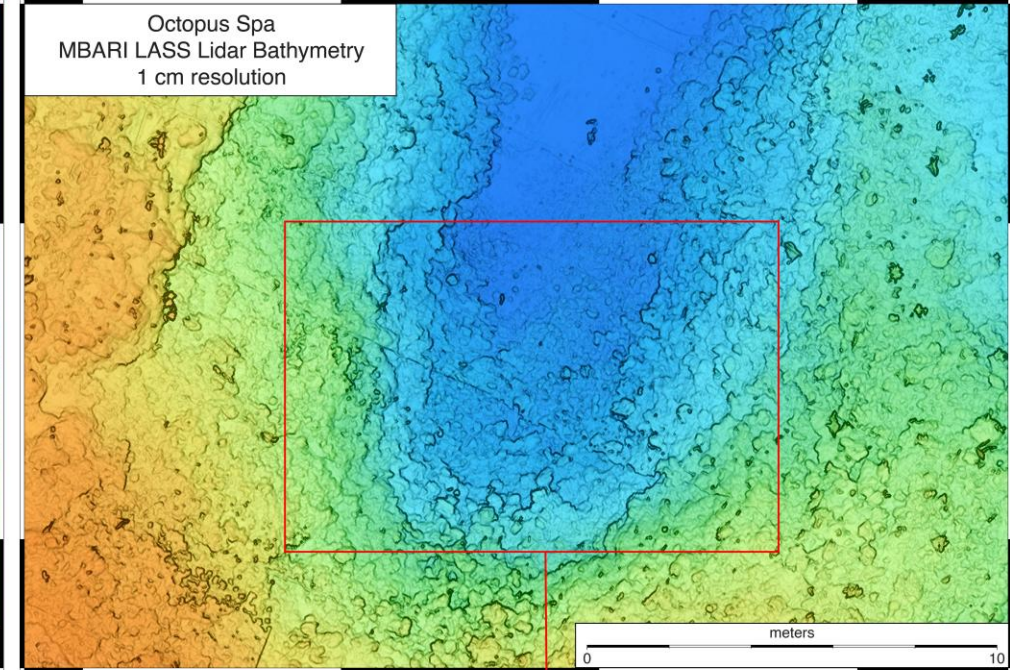
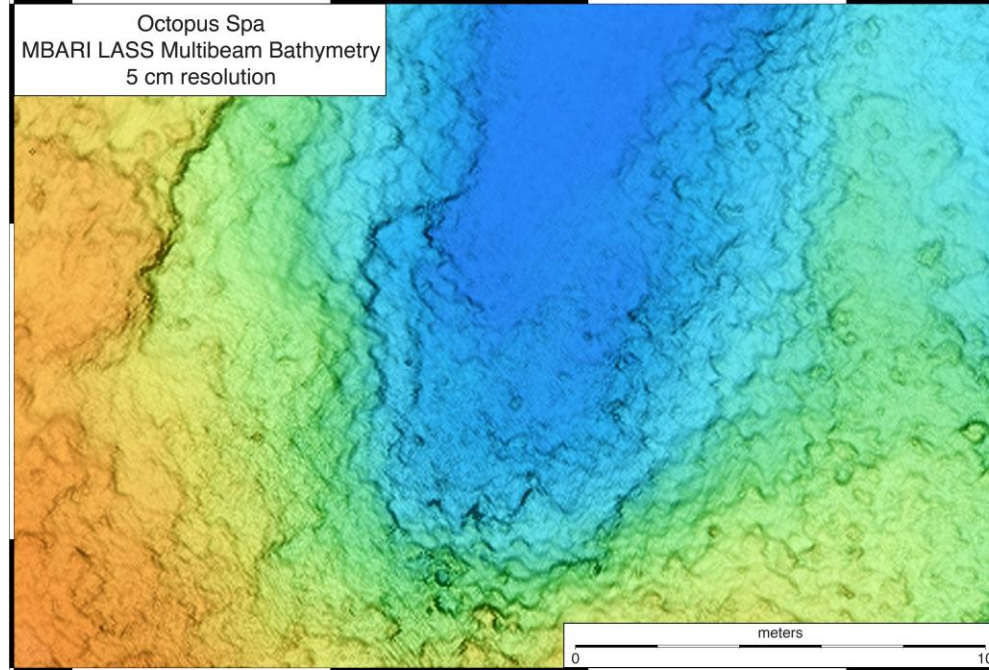


0 meters

Stereo still  
cameras  
(2 mm)



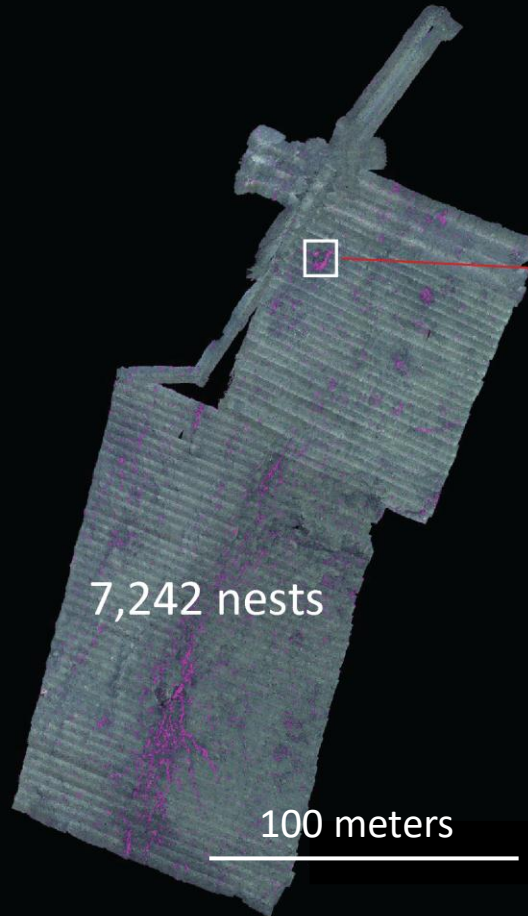




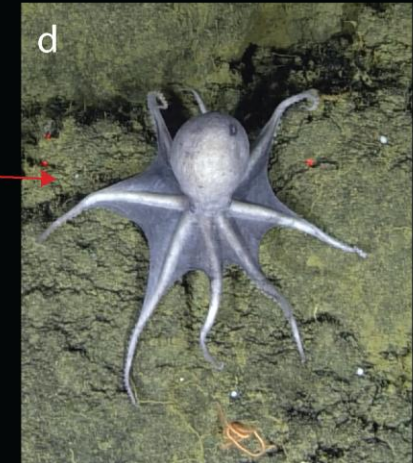
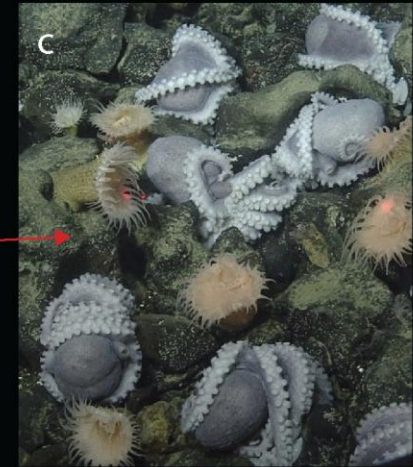
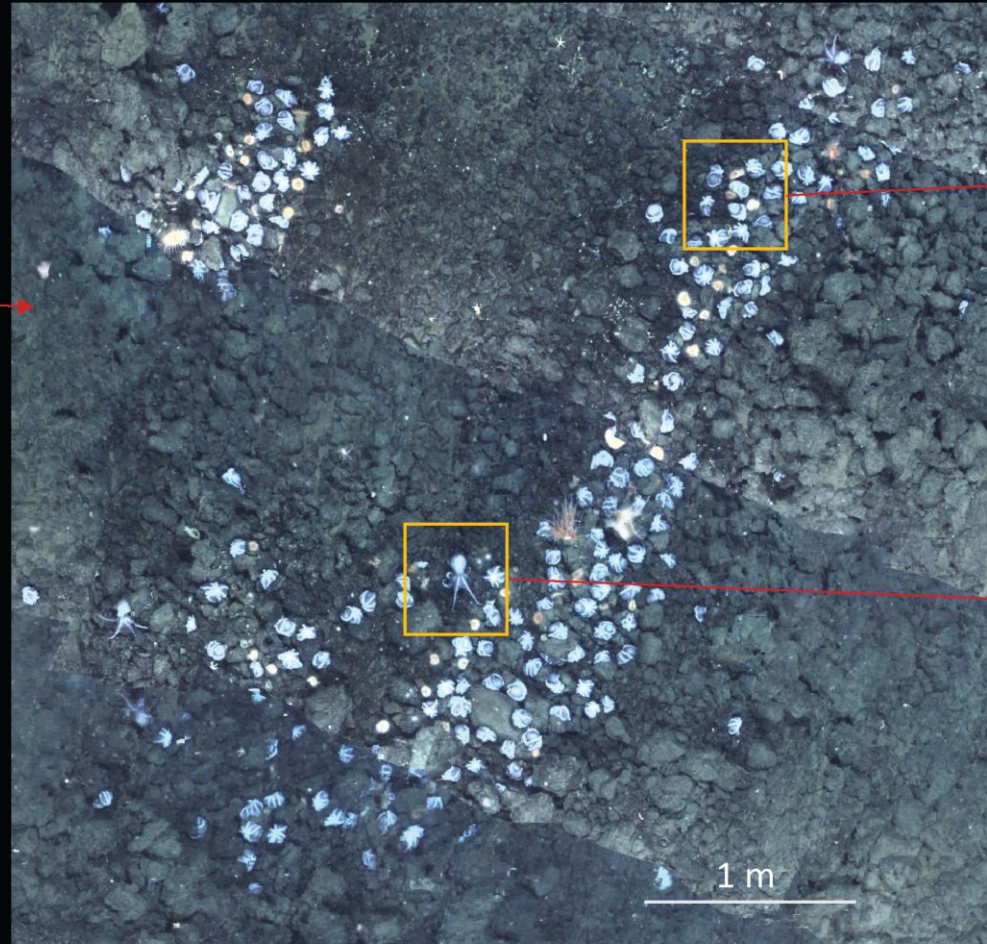


# Interpreting the mapping

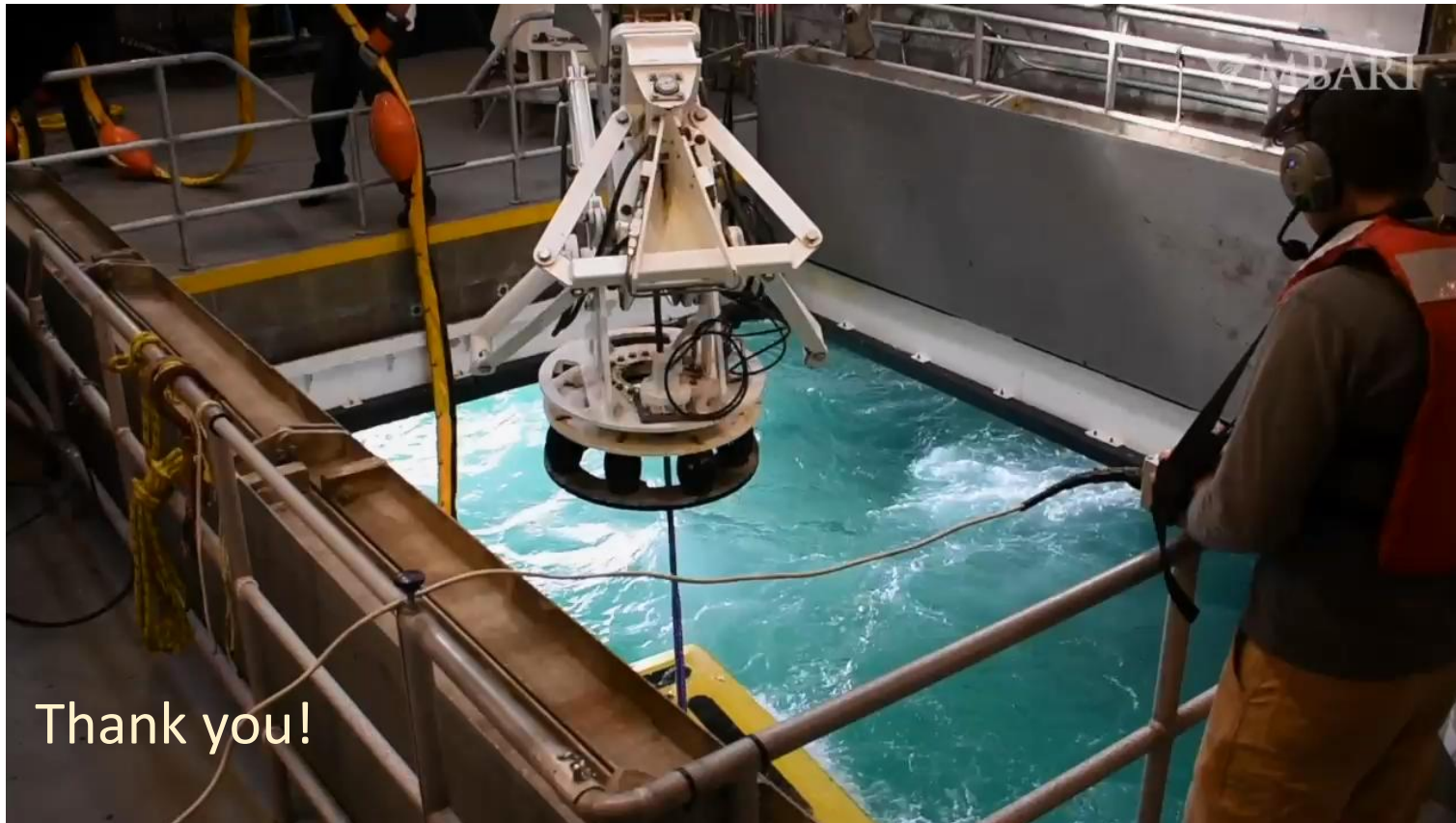
a) LASS photomosaic



b) Zoom in on photomosaic: individuals brooding and moving



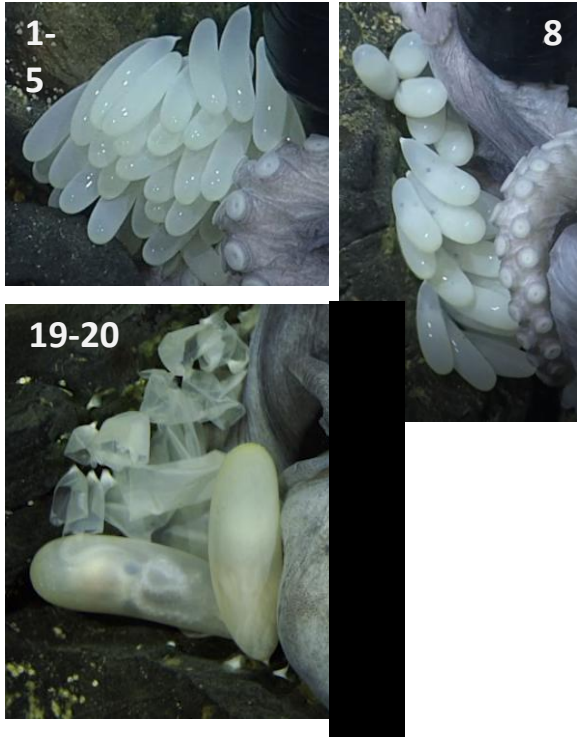
*Muusoctopus* from ROV video



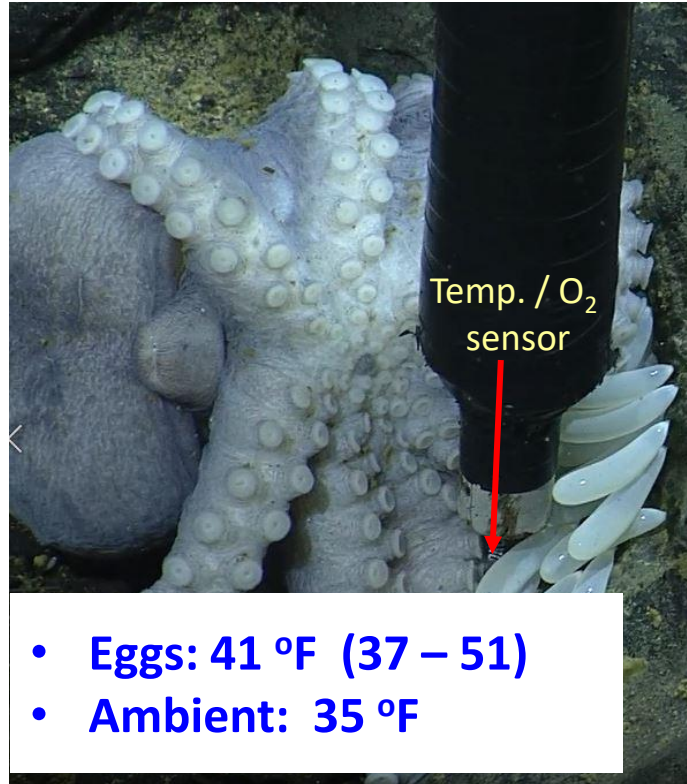


# Measurements of marked nests

## Embryo stage rating



## Egg temperature / oxygen



## Female Turnover



We welcome contributions from developers,  
researchers, and industry professionals  
interested in advancing 3D web technologies.



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